

On an extended recurrent Riemannian manifold

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Abstract

The object of the present paper is to introduce a type of recurrent Riemannian manifold called extended recurrent Riemannian manifold . The existence of extended recurrent Riemannian manifold is also shown by one non trivial example.

Subject Classification: 53C15 and 53C25.

Keywords: Generalized recurrent manifold, cyclic Ricci tensor, codazzi type Ricci tensor, concurrent vector field.

1 Introduction:

Recurrent spaces have been of great importance and were studied by a large number of authors such as Ruse [1], Patterson [2] , Walker [3], Singh and Khan ([4] and [5]) etc. In 1991, De and Guha introduced and studied generalized recurrent manifold whose curvature tensor $R(X,Y)Z$ of type (1,3) satisfies the condition:

$$(1.1) \quad (D_U R)(X, Y)Z = A(U)R(X, Y)Z + B(U)[g(Y, Z)X - g(X, Z)Y],$$

where A and B are two 1-forms, B is non-zero and D denoted the operator of covariant differentiation with respect to metric tensor g . Such a space has been denoted by GK_n . In recent papers Bandyopadhyay [7], Prakasha and Yildiz [8], Khan [9] etc explored various geometrical properties by using generalized recurrent manifold on Sasakian manifold and Lorentzian α -Sasakian manifold.

Further one of the author Prasad [10] considered a non-flat Riemannian manifold (M^n, g) ($n > 2$) whose curvature tensor R satisfies the following condition

$$(1.2) \quad (D_U R)(X, Y)Z = A(U)R(X, Y)Z + B(U)g(Y, Z)X,$$

where A and B are two non-zero 1-forms and D has the meaning already mentioned. Such a manifold called by the author as semi-generalized recurrent manifold and denoted by $(SGK)_n$. Singh, Singh and Kumar [11], [12] and Chaudhary, Kumar and Singh [13] extended this notation to Lorentzian α -Sasakian manifold, P-Sasakian manifold and trans-Sasakian manifold.

The object of the present paper is to study a type of non-flat recurrent Riemannian manifold (M^n, g) ($n > 2$) whose curvature tensor $R(X, Y)Z$ of the type (1,3) satisfies the condition

$$(1.3) \quad (D_U R)(X, Y)Z = A(U)R(X, Y)Z + B(U)g(Y, Z)X + C(U)g(X, Z)Y,$$

where A , B and C are three non-zero 1-forms and ρ_1 , ρ_2 and ρ_3 are three vector fields such that

$$(1.4) \quad g(U, \rho_1) = A(U), \quad g(U, \rho_2) = B(U) \text{ and } g(U, \rho_3) = C(U).$$

Such a manifold shall be called as an extended recurrent Riemannian manifold and 1-forms A , B and C shall be called its associated 1-forms and n -dimensional recurrent manifold of this kind shall be denoted by $(ER)_n$.

If in particular we replace C by $-B$ then (1.3) becomes (1.1).

If in particular $C=0$, then (1.3) becomes (1.2).

If in particular $B=0$ and $C=0$, then the space reduced to a recurrent space according to Ruse [14] and Walker [3].

Moreover, in particular if $A=B=C=0$ then (1.3) becomes $(D_U R)(X, Y)Z=0$. That is, a Riemannian manifold is symmetric accordingly Kobayashi and Nomizu [15] and Desai and Amer [16]. This justifies the name "extended recurrent Riemannian manifold" for the manifold defined by (1.3) and the use of the symbol $(ER)_n$ for it.

In this paper the necessary and sufficient condition for constant scalar curvature of $(ER)_n$ is obtained. Extended recurrent manifold with cyclic Ricci tensor and Codazzi type Ricci tensor are studied. It is also show that if $(ER)_n$ admits a concurrent vector field V then V is not orthogonal to ρ_2 and ρ_3 . Finally a non-trivial example of $(ER)_n$ has been constructed.

2 Preliminaries:

Let S and r denote the Ricci tensor of type (0,2) and scalar curvature respectively and Q denote the symmetric endomorphism of the tangent space at each point corresponding to the Ricci tensor, i.e.

$$(2.1) \quad S(X, Y) = g(QX, Y),$$

for any vector field X and Y .

For(1.3), we get

$$(2.2) \quad (D_U S)(Y, Z) = A(U)S(Y, Z) + [nB(U) + C(U)]g(Y, Z).$$

Contracting (2.2), we have

$$(2.3) \quad dr(U) = Ur = rA(U) + n[nB(U) + C(U)].$$

3 Nature of the 1-forms A,B and C on an extended recurrent space:

From (2.3) suppose $r = 0$, then

$$(3.1) \quad \begin{aligned} nB(U) + C(U) &= 0 \\ \Rightarrow B(U) &= -\frac{1}{n}C(U), \end{aligned}$$

Hence we have the following theorem

Theorem 1. *If the scalar curvature tensor of extended recurrent is zero, then the 1-form B and C are proportional.*

Now we consider $(ER)_n$ is of constant scalar curvature then from (2.3), we have

$$(3.2) \quad nB(U) + C(U) = -\frac{r}{n}A(U).$$

Again if (3.2) holds, then from (2.3), we get

$$\begin{aligned} dr(U) &= 0, \\ r &= \text{constant} \end{aligned}$$

Hence, we can state the following theorem:

Theorem 2. *An $(ER)_n$ is of constant curvature if and only if (3.2) holds.*

Now taking covariant derivative of (3.2) with respect to V , we get

$$(3.3) \quad (D_V A)(U)r + n[n(D_V B)U + (D_V C)(U)] = 0.$$

Interchanging U and V in (3.3) and then subtracting, we get

$$(3.4) \quad [(D_V A)(U)r - (D_U A)(V)]r + n[n\{(D_V B)(U) - (D_U B)(V)\} + \{D_V C(U) - (D_U C)(V)\}] = 0.$$

Thus we have the following theorem:

Theorem 3. *In an extended recurrent space of non-zero constant scalar curvature r , the 1-forms A is closed if and only if 1-forms B and C are closed.*

Next we consider the case when the scalar curvature r is not constant. From (2.3) it follows that

$$(3.5) \quad VUr = (D_V A)(U)r + A(U)(Vr) + n[n(D_V B)(U) + (D_V C)(U)]$$

Interchanging U and V in (3.5) and then subtracting, we get

$$(3.6) \quad [(D_V A)(U) - (D_U A)(V)]r + n[n\{(D_V B)(U) - (D_U B)(V)\} + \{D_V C(U) - (D_U C)(V)\}] + n[n\{A(U)B(V) - A(V)B(U)\} + \{A(U)C(V) - A(V)C(U)\}] = 0.$$

Thus we have the following theorem:

Theorem 4. *In an extended recurrent space of non-zero constant scalar curvature r , the 1-forms A , B and C cannot be closed unless the 1-forms A is collinear with the 1-forms B and C .*

Permuting equation (1.3) twice with respect to U, X, Y adding the three equation and using Bianchi's second identity, we have

$$(3.7) \quad [A(U)R(X, Y)Z + A(X)R(Y, U)Z + A(Y)R(U, X)Z] + g(Y, Z)[B(U)X + C(X)U] + g(X, Z)[C(U)Y + B(Y)U] + g(U, Z)[C(Y)X + B(X)Y] = 0$$

Contracting (3.7) with respect to X , we get

$$(3.8) \quad A(U)S(Y, Z) - A(Y)S(U, Z) - R(Y, U, \rho_1, Z) + n[B(U)X + 2C(U)]g(Y, Z) + [nC(Y) + 2B(Y)]g(U, Z) = 0.$$

Using (2.1) in (3.8), we have

$$A(U)g(QY, Z) - A(Y)g(QU, Z) - g(R(Y, U)\rho_1, Z) + n[B(U)X + 2C(U)]g(Y, Z) + [nC(Y) + 2B(Y)]g(U, Z) = 0.$$

Factoring off Z , we get

$$(3.9) \quad A(U)QY - A(Y)QU - R(Y, U)\rho_1 + n[B(U) + 2C(U)]Y + [nC(Y) + 2B(Y)]U = 0.$$

Contracting (3.9) with respect to Y , we have

$$(3.10) \quad S(U, \rho_1) = \frac{1}{2}rg(U, \rho_1) + \left(\frac{n^2 + 2}{2}\right)B(U) + \frac{3n}{2}C(U).$$

Hence we have the following theorem:

Theorem 5. *If $(ER)_n$ satisfies second Bianchi identity then $\frac{r}{2}$ is an eigen value of Ricci S and ρ_1 is an eigen vector corresponding to the eigen value if only if $(n^2 + 2)B(U) + 3nC(U) = 0$.*

4 $(ER)_n$ with cyclic Ricci tensor:

In this section we consider an $(ER)_n$ in which the Ricci tensor is a cyclic tensor, i.e.

$$(4.1) \quad (D_X S)(Y, Z) + (D_Y S)(Z, X) + (D_Z S)(X, Y) = 0,$$

which implies

$$(4.2) \quad dr(X) = 0.$$

From (1.3), we have

$$(4.3) \quad dr(X) = A(X)r + n[nB(X) + C(X)].$$

Therefore from (4.2) and (4.3), we get

$$(4.4) \quad A(X)r + n[nB(X) + C(X)] = 0.$$

From (4.1), we have

$$A(X)S(Y, Z) + A(Y)S(Z, X) + A(Z)S(X, Y) + n[B(X)g(Y, Z) + B(Y)g(X, Z) + B(Z)g(X, Y)] + [C(X)g(Y, Z) + C(Y)g(X, Z) + C(Z)g(X, Y)] = 0,$$

which yields on contraction

$$(4.5) \quad A(X)r + 2A(QX) + n(n+2)B(X) + (n+2)C(X) = 0.$$

Now in view of (4.4) and (4.5), we get

$$(4.6) \quad \begin{aligned} A(QX) &= \frac{r}{n}A(X) \\ \text{or } S(U, \rho_1) &= \frac{r}{n}g(X, \rho_1). \end{aligned}$$

Hence we have the following theorem:

Theorem 6. *If $(ER)_n$ has cyclic Ricci tensor, then $\frac{r}{n}$ is an eigen value of Ricci tensor S and ρ_1 is an eigen vector corresponding to the eigen value.*

5 $(ER)_n$ with Codazzi type of Ricci tensor:

In this section we consider an $(ER)_n$ in which the Ricci tensor is a Codazzi type of Ricci tensor Ferus [17]

$$(5.1) \quad (D_X S)(Y, Z) = (D_Z S)(Y, X).$$

By view of Bianchi identity and (5.1), we have

$$(5.2) \quad (\text{div}R)(X, Y)Z = 0.$$

In view of (1.3), we get on contraction

$$(5.3) \quad (\text{div}R)(X, Y)Z = A(R(X, Y)Z) + B(X)g(Y, Z) + C(Y)g(X, Z).$$

Now using (5.2) in (5.3), we get

$$(5.4) \quad A(R(X, Y)Z) + B(X)g(Y, Z) + C(Y)g(X, Z) = 0.$$

In view of (5.4), we get

$$(5.5) \quad A(QX) = -nB(X) - C(X).$$

From (2.2) and (5.1), we have

$$(5.6) \quad \begin{aligned} A(X)S(Y, Z) - A(Z)S(Y, X) + [nB(X) + \\ C(X)]g(Y, Z) - [nB(Z) + C(Z)]g(X, Y) = 0. \end{aligned}$$

On contracting of (5.6), we have

$$(5.7) \quad A(X)r = A(QX) - (n-1)[nB(X) + C(X)].$$

Using (5.5) and (5.7) in (2.3), we have

$$(5.8) \quad dr(X) = 0.$$

Again it is known [18] that in a Riemannian manifold (M^n, g) ($n > 3$)

$$(5.9) \quad (\text{div}C)(X, Y)Z = \frac{n-3}{n-2}[(D_X S)(Y, Z) - (D_Z S)(Y, X)] + \frac{1}{2(n-1)}[g(X, Y)dr(Z) - g(Y, Z)dr(X)],$$

where C denotes the conformal curvature.

As a consequences of (5.1) and (5.8), (5.9) reduces to

$$(\text{div}C)(X, Y)Z = 0,$$

which shows that the tensor is conservative [19].

Hence we can state the following theorem:

Theorem 7. *If in an $(ER)_n$ the Ricci tensor is a Codazzi tensor then its conformal curvature tensor is conservative.*

6 Extended recurrent with concurrent vector field:

In this section first we suppose that the $(ER)_n$ admits a concurrent unit vector field V ,

$$(6.1) \quad D_X V = \rho X,$$

where ρ is a non-zero constant .

By Ricci-identity

$$(6.2) \quad R(X, Y)V = 0.$$

Taking covariant derivative of (6.2), we get

$$(6.3) \quad (D_W R)(X, Y)V = -\rho R(X, Y)W$$

Also by definition of $(ER)_n$, we find

$$(6.4) \quad (D_W R)(X, Y)V = A(W)R(X, Y)V + B(W)g(Y, V)X + C(W)g(X, V)Y.$$

In view of (6.2), (6.3) and (6.4), we get

$$(6.5) \quad -\rho R(X, Y)W = B(W)g(Y, V)X + C(W)g(X, V)Y.$$

On contraction, we find

$$(6.6) \quad -\rho S(Y, W) = nB(W)g(Y, V) + C(W)g(Y, V).$$

Again on contraction, we get

$$(6.7) \quad -\rho r = ng(\rho_2, V) + g(\rho_3, V),$$

Since $\rho \neq 0$ and $r \neq 0$, then from (6.7), we get

$$(6.8) \quad ng(\rho_2, V) + g(\rho_3, V) \neq 0.$$

Hence we have the following theorem:

Theorem 8. *If an $(ER)_n$ admits a concurrent unit vector field V , then V is not orthogonal to ρ_2 and ρ_3 , where ρ_2 and ρ_3 are the associated vector field to the 1-forms B and C .*

7 Extended conformally recurrent Riemannian manifolds:

The conformal curvature tensor C on a manifold of dimension n is defined by

$$(7.1) \quad C(X, Y)Z = R(X, Y)Z - \frac{1}{n-2}[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY] + \frac{r}{(n-1)(n-2)}[g(Y, Z)X - g(X, Z)Y].$$

Taking covariant derivative of (7.1) with respect to 'U', we get

$$(7.2) \quad (D_U C)(X, Y)Z = (D_U R)(X, Y)Z - \frac{1}{n-2}[(D_U S)(Y, Z)X + (D_U S)(X, Z)Y + g(Y, Z)(D_U Q)X - g(X, Z)(D_U Q)Y] + \frac{D_U r}{(n-1)(n-2)}[g(Y, Z)X - g(X, Z)Y].$$

Using (1.3), (2.2) and (2.3), in (7.2), we get

$$(7.3) \quad (D_U C)(X, Y)Z = A(U)R(X, Y)Z - \frac{1}{n-2}A(U)[S(Y, Z)X + S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY] + \frac{r}{(n-1)(n-2)}A(U)[g(Y, Z)X - g(X, Z)Y] - \frac{1}{n-1}[B(U) + C(U)][g(Y, Z)X - ng(X, Z)Y]$$

From (7.1) and (7.3), we get

$$(7.4) \quad (D_U C)(X, Y)Z = A(U)C(X, Y)Z - \frac{1}{n-1}[B(U) + C(U)][g(Y, Z)X - ng(X, Z)Y]$$

Theorem 9. *An extended conformally recurrent Riemannian manifold is conformally recurrent if and only if $B(U) + C(U) = 0$ i.e. manifold reduces to generalized recurrent.*

8 Example:

Let us consider the 3-dimensional manifold $M = \{(x, y, z) \in R^3, z \neq 0\}$, where (x, y, z) are standard co-ordinate of R^3 .

We choose the vector fields

$$(8.1) \quad e_1 = e^{-2z} \frac{\partial}{\partial y}, \quad e_2 = \frac{\partial}{\partial z}, \quad e_3 = e^{-2z} \frac{\partial}{\partial x}$$

which is linearly independently at each point of M .

Let g be the Riemannian metric denoted by

$$(8.2) \quad g(e_i, e_j) = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

Then from equation (8.1), we have

$$(8.3) \quad [e_1, e_2] = 2e_1, [e_1, e_3] = 0, [e_2, e_3] = -2e_3.$$

By Koszul's formula

$$(8.4) \quad 2g(D_X Y, Z) = Xg(Y, Z) + Yg(X, Z) - Zg(X, Y) - g(X, [Y, Z]) \\ - g(Y, [X, Z]) + g(Z, [X, Y]),$$

Using (8.2) and (8.3) in (8.4), we get

$$(8.5) \quad \begin{aligned} D_{e_1} e_1 &= -2e_2, & D_{e_1} e_2 &= 2e_1, & D_{e_1} e_3 &= 0, \\ D_{e_2} e_1 &= 0, & D_{e_2} e_2 &= 0, & D_{e_2} e_3 &= 0, \\ D_{e_3} e_1 &= 0, & D_{e_3} e_2 &= 2e_3, & D_{e_3} e_3 &= -2e_2. \end{aligned}$$

The curvature tensor is given by

$$(8.6) \quad R(X, Y)Z = D_X D_Y Z - D_Y D_X Z - D_{[X, Y]} Z$$

Using (8.3) and (8.5) in (8.6), we get

$$(8.7) \quad \begin{aligned} R(e_1, e_2)e_1 &= 4e_2, & R(e_1, e_2)e_2 &= -4e_1, & R(e_1, e_2)e_3 &= 0 \\ R(e_2, e_3)e_1 &= 0, & R(e_2, e_3)e_2 &= 4e_3, & R(e_2, e_3)e_3 &= -4e_2 \\ R(e_1, e_3)e_1 &= 0, & R(e_1, e_3)e_2 &= 0, & R(e_1, e_3)e_3 &= -4e_1 \\ R(e_1, e_1)e_1 &= R(e_1, e_1)e_2 = R(e_1, e_1)e_3 = 0 \\ R(e_2, e_2)e_1 &= R(e_2, e_2)e_2 = R(e_2, e_2)e_3 = 0 \\ R(e_3, e_3)e_1 &= R(e_3, e_3)e_2 = R(e_3, e_3)e_3 = 0. \end{aligned}$$

Let X, Y and Z be any three vector fields given by

$$(8.8) \quad X = a_1 e_1 + b_1 e_2 + c_1 e_3, \quad Y = a_2 e_1 + b_2 e_2 + c_2 e_3, \quad Z = a_3 e_1 + b_3 e_2 + c_3 e_3,$$

where a_i, b_i and c_i are the set of all positive real numbers, $i = 1, 2, 3$.

$$(8.9) \quad \begin{aligned} R(X, Y)Z &= pe_1 + qe_2 + re_3 \\ g(Y, Z)X &= le_1 + me_2 + ne_3 \\ g(X, Z)Y &= ue_1 + ve_2 + we_3 \end{aligned}$$

where

$$\begin{aligned} p &= 4[a_2(b_1b_3 + c_1c_3) - a_1(b_2b_3 + c_2c_3)], \\ q &= 4[b_2(a_1a_3 + c_1c_3) - b_1(a_2a_3 + c_2c_3)], \\ r &= p = 4b_3(b_1c_2 - b_2c_1), \\ l &= a_1(a_2a_3 + b_2b_3 + c_2c_3), \\ m &= b_1(a_2a_3 + b_2b_3 + c_2c_3), \\ n &= c_1(a_2a_3 + b_2b_3 + c_2c_3), \\ u &= a_2(a_1a_3 + b_1b_3 + c_1c_3), \\ v &= b_2(a_1a_3 + b_1b_3 + c_1c_3), \\ w &= c_2(a_1a_3 + b_1b_3 + c_1c_3). \end{aligned}$$

By view of the equation (8.5), (8.7), (7) and (8.9), we have

$$(8.10) \quad (D_{e_i}R)(X, Y)Z = D_{e_i}R(X, Y)Z - R(D_{e_i}X, Y)Z - R(X, D_{e_i}Y)Z - R(X, Y)D_{e_i}Z$$

where

$$\begin{aligned} u_1 &= 8[2(b_2c_1c_3 - a_2a_3b_1) - b_1c_2c_3 + a_1b_3c_2 + b_1b_2b_3], \\ v_1 &= 8[-2a_2b_1b_3 - a_2c_1c_3 + a_1c_2c_3 - a_1a_3c_2 - a_3b_1b_2], \\ w_1 &= 8[a_2b_3c_1 - a_3b_2c_1], u_2 = v_2 = w_2 = 0, \\ u_3 &= 0, v_3 = 8[-b_1b_3c_2 + b_2b_3c_1 - a_2a_3c_1 + a_1a_3c_2], \\ w_3 &= 8[a_1a_3b_2 - a_2a_3b_1]. \end{aligned}$$

Consequently, the manifold under consideration is not recurrent. Let us now consider 1-form non vanishes

$$(8.11) \quad \begin{aligned} A(e_i) &= \frac{u_i(nv - mw) + v_i(nu - lw) + w_i(lv - mu)}{u(nq - mr) + v(lr - pn) + w(pm - lq)} \\ B(e_i) &= \frac{u_i(wq - vr) + v_i(ur - pw) + w_i(pv - qu)}{u(nq - mr) + v(lr - pn) + w(pm - lq)} \\ C(e_i) &= \frac{u_i(nq - mr) + v_i(lr - np) + w_i(mp - lq)}{u(nq - mr) + v(lr - pn) + w(pm - lq)}. \end{aligned}$$

Thus, we have

$$A(e_i) = B(e_i) = C(e_i) = 0 \text{ for } i = 2.$$

s.t

$$u(nq - mr) + v(lr - pn) + w(pm - lq) \neq 0.$$

From (1.3), we have

$$(8.12) \quad (D_{e_i}R)(X, Y)Z = A(e_i)R(X, Y)Z + B(e_i)g(Y, Z)X + C(e_i)g(X, Z)Y.$$

By virtue of (8.9), (8.10) and (8.11), it can be easily seen that the Riemannian manifold satisfies relation (8.12). Hence the manifold under consideration is an extended recurrent Riemannian manifold (M^3, g) , which is neither recurrent nor generalized recurrent. This leads to the following theorem:

Theorem 10. *There exist an extended recurrent Riemannian manifold (M^3, g) , which is neither recurrent nor generalized recurrent.*

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